

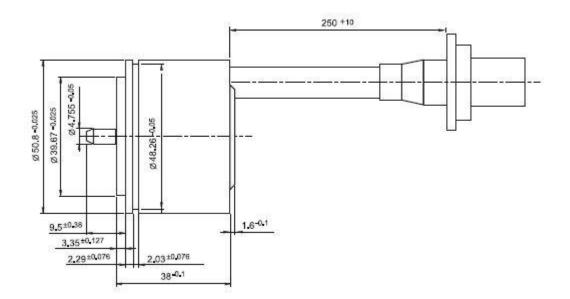
MR-2003

Multispeed (X1 and X6) Resolver

The MR-2003 is a multi-speed resolver. A special design for stator/rotor slot combination optimization, common space harmonics reduction and angular accuracy improvement. The increased number of pole-pairs effectively increases system resolution, proportionately, reducing the number of rotational degrees represented by one complete electrical cycle. Multi-pole design has averaging effect on any local mechanical/winding perturbation. Number of pole-pairs (referred to as resolver "speed") diminishes any effect of combined system errors with, as a result, enhanced system performance, repeatability and reliability.



Drawing





Specifications

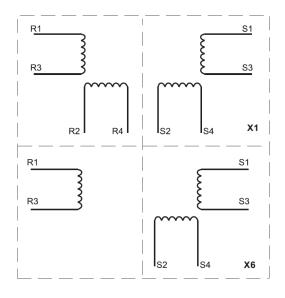
Parameter		Unit	Value	Tolerance
Function CX (transmitter) Rotation: Full Speeds: 1X and 6X			<u></u>	
Input Voltage		V (rms)	8 – 26	± 5%
Input Frequency		Hz	380 – 2100	-
DC resistance: Rotor 1X Stator 1X Rotor 6X Stator 6X		Ohm Ohm Ohm Ohm	215 140 95 155	± 10% ± 10% ± 10% ± 10%
Impedance: 1X 6X		Ohm Ohm Ohm Ohm Ohm	Zro=300 + j 2100 Zso = 220 + j 70 Zrs = 800 + j 330 Zro= 110 + j 70 Zso = 150 + j 150 Zrs = 120 + j 60	± 30% ± 30% ± 30% ± 30% ± 30%
Transformation ratio		%	0.454	± 5%
Phase shift:				
1X 6X		deg deg	13.5° 58.0°	± 15% ± 15%
Phase shift vs. temperature:				
1X 6X		deg deg	4% per ⁰C 4% per ⁰C	-
Null Voltage: Rotor 1X Rotor 6X		mV(rms) mV(rms)	30 20	max max
Accuracy: 1X 6X		arc min arc min	≤10.0 ≤1.5	-
Zero marking withstanding: Per MIL-S-81963		deg	±2	-
Dielectric withstanding: Per MIL-S-81963				
Insulation between windings	MΩ at 250V AC		100	min
Ŭ		at 500V AC	100	min
Weight		gr	450	± 5%

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Wiring Diagram



Phase Equation

E (S1-S3) = KE(R1-R3) cos n θ E (S2-S4) = KE(R1-R3) sin n θ where: K - transformation ratio n - resolver speed

For Additional Information

To learn more about the MR-2003

Resolver or other MTC products, contact MTC

on +972 4 998 7772 or email marketing@mtcind.com

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